

# MRI in a magnetized Taylor-Couette flow — preparatory studies for upcoming DRESDYN-MRI experiments

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# Outline

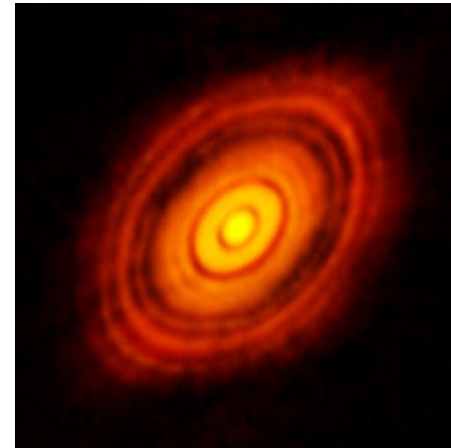
- MRI: from astrophysics to laboratory
- DRESDYN facility at HZDR
- Theoretical results on the linear and nonlinear dynamics of MRI for the upcoming DRESDYN-MRI experiments
- Summary and future work

# Magnetorotational Instability (MRI)

**Magnetorotational instability (MRI)** is a powerful dynamical instability arising as a result of the combined effects of differential rotation (shear) and a background magnetic field

MRI is amongst the most important instabilities in astrophysics, driving angular momentum transport, dynamo and mass transport in accretion disks and stars

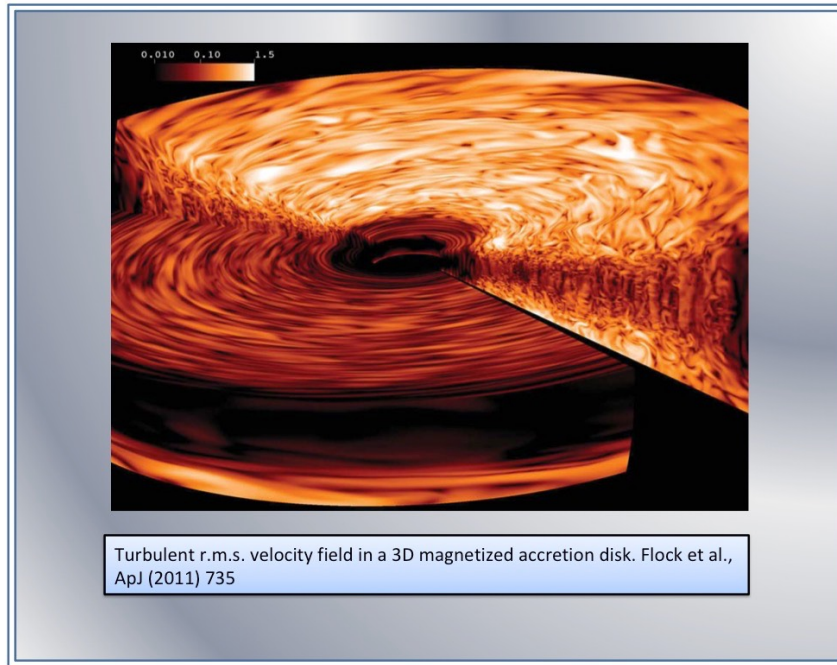
AD around  
Black Hole  
(NASA)



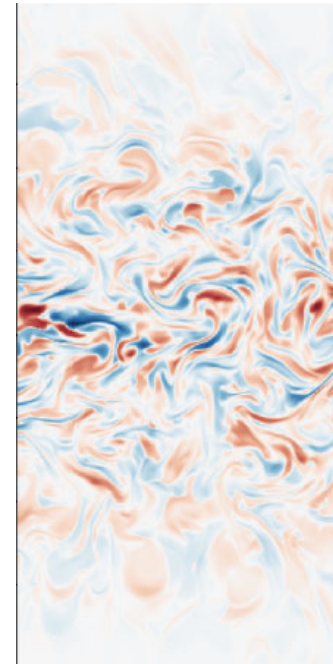
ALMA image of  
HL Tauri  
(Mueller et al. 2018)

# Structure of MRI-turbulence

Sustained MHD turbulence driven by MRI was first demonstrated in the 90s via simulations in the shearing box model and extensively studied by many groups since then



Flock et al. (2011)



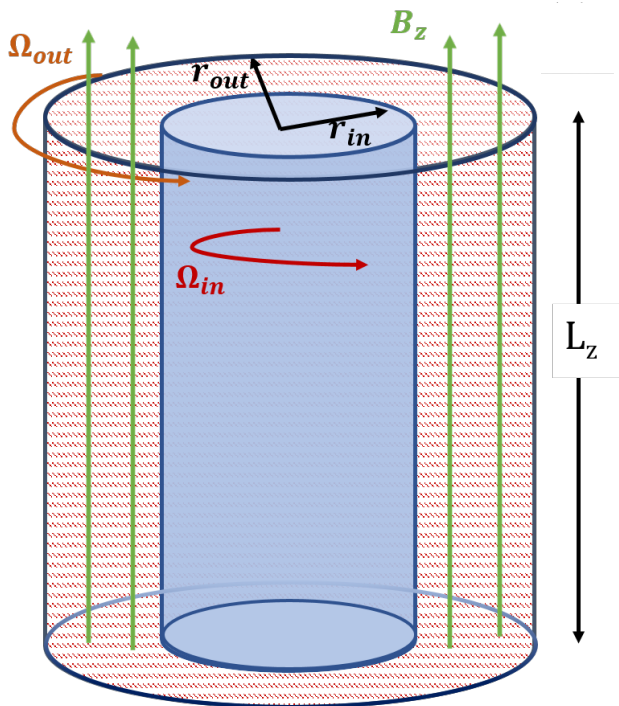
Held et al. (2024)

Turbulence is magnetically dominated — predominantly Maxwell stress of the turbulent magnetic field is responsible for most of outward transport of angular momentum and hence mass accretion

# MRI in the laboratory

Interest and efforts in the laboratory detection and studies of MRI since the 2000s

Taylor-Couette (TC) flow threaded by an external magnetic field is a basic setup used in MRI-experiments in the laboratory due to its analogy with accretion disks



Working substance: liquid metals (GalSn, Sodium) with very small magnetic Prandtl numbers

$$Pm = \nu/\eta \sim 10^{-6} - 10^{-5}$$

$\nu$  – viscosity

$\eta$  – magnetic diffusivity

# Previous theory and experiments on MRI in TC flows

The first linear analysis of MRI with an imposed constant vertical magnetic field  $B_{0z}$  so-called **Standard MRI (SMRI)**, in viscous and resistive TC flows theoretically showed its plausibility under laboratory conditions in the 2000s

(e.g., Ji et al. 2001, Goodman & Ji 2002, Rüdiger et al. 2003)

Moreover, **inductionless** forms of MRI were revealed in these TC flows:

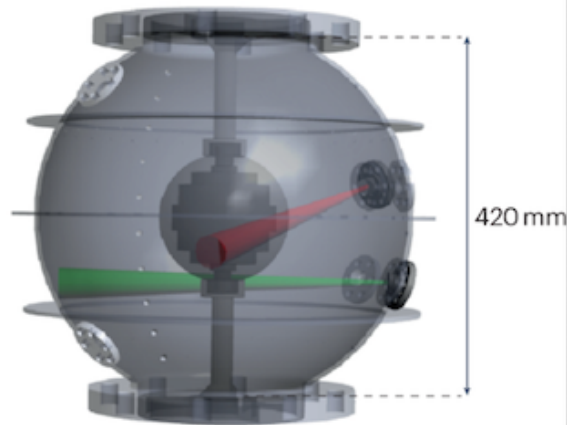
— **Helical MRI (HMRI)** with an imposed helical  $B_{0\phi} + B_{0z}$  magnetic fields

(Hollerbach & Rüdiger 2005, Liu et al. 2006, Priede 2007)

— **Azimuthal MRI (AMRI)** with an imposed  $B_{0\phi}$  azimuthal field

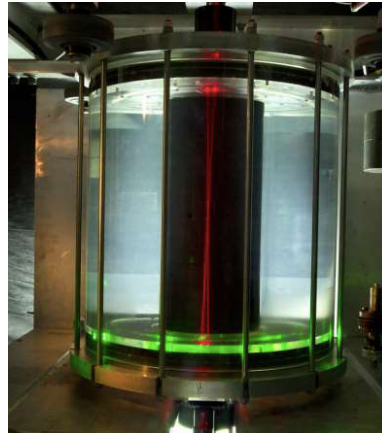
(Rüdiger et al. 2007, Hollerbach et al. 2010)

## Maryland MRI-exp.



**Claimed MRI detection  
but in fact turned to be  
Shercliff layer instability**  
(Sisan et al. 2004)

## Princeton MRI-exp.



**Detected magnetocoriolis  
waves/Shercliff layer instability,**  
(Nornberg et al. 2010  
Roach et al. 2012  
Caspary et al. 2018  
Wang et al. 2022)

## PROMISE



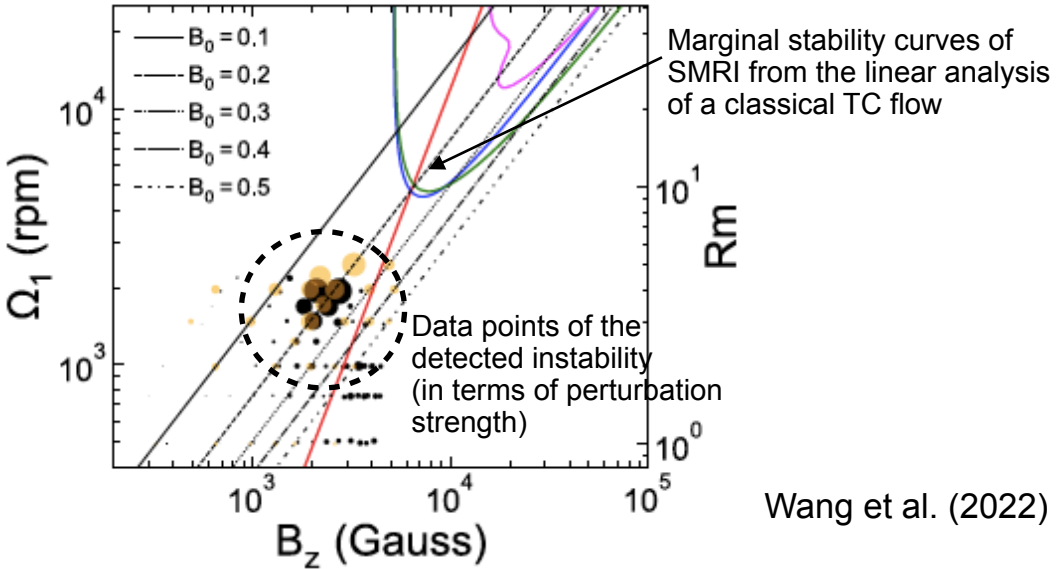
**Detected HMRI, AMRI and  
Taylor instability**  
(Stefani et al. 2006, 2009  
Seilmayer et al. 2012, 2014)

**SMRI could NOT be definitively detected by that time** — the main challenge was to reach high enough magnetic Reynolds numbers  $Rm \sim 10$  and field strength needed for the excitation of SMRI, resulting in very high Reynolds numbers  $Re \sim 10^6$  due to very small  $Pm = \nu/\eta = Rm/Re \lesssim 10^{-5}$  of liquid metals

In 2022, the Princeton group (Wang et al. 2022) found some experimental evidence for axisymmetric and non-axisymmetric SMRI, **BUT**

— the detected instabilities occur at much lower critical  $Rm_c \sim 3$  and axial field  $B_{0z,c} \sim 2000G$  than linear analysis in the classical TC flow predicts  $Rm_c \sim 10, B_{0z,c} \sim 5000G$  (Mishra et al. 2022, Rüdiger & Schultz 2024)

— axisymmetric and non-axisymmetric unstable modes appear very close to each other in the  $(Rm, B_{0z})$ - plane



These experimental findings on SMRI detection although quite promising, are still tentative, which should be confirmed and further studied/clarified



# DRESDYN Project

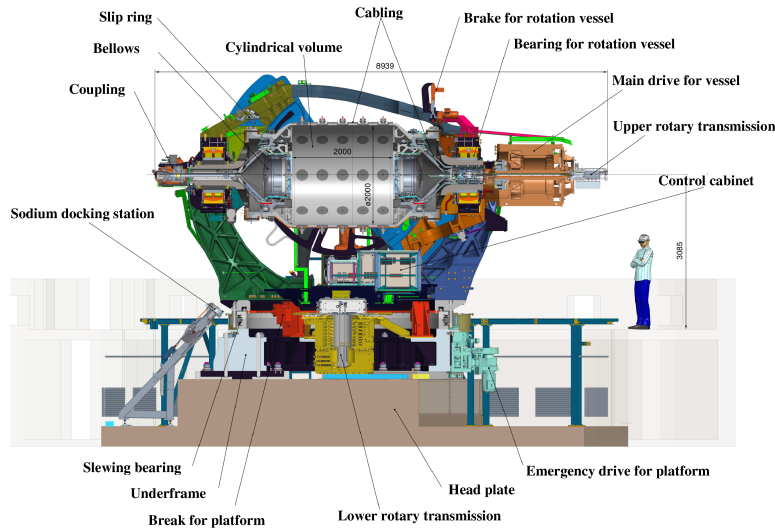
New generation of precession dynamo and MRI experiments at HZDR

# DRESDYN — DREsden Sodium facility for DYNamo studies — is a platform for large-scale liquid sodium experiments devoted to fundamental geo- and astrophysical as well as to various applied problems

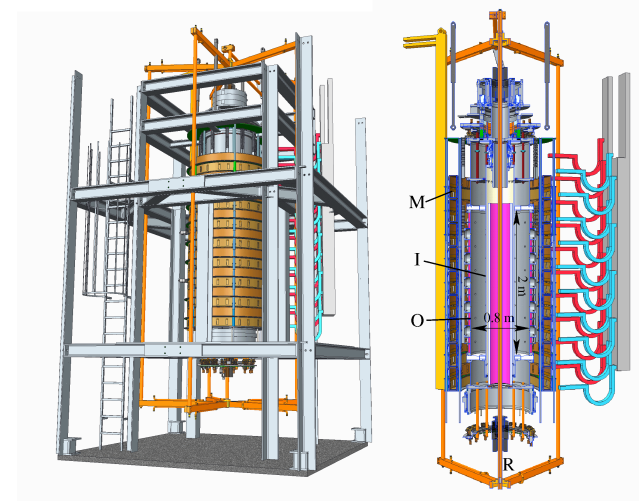


Stefani et al.: Geophys. Astrophys. Fluid Dyn. (2019)

## Precession dynamo experiment

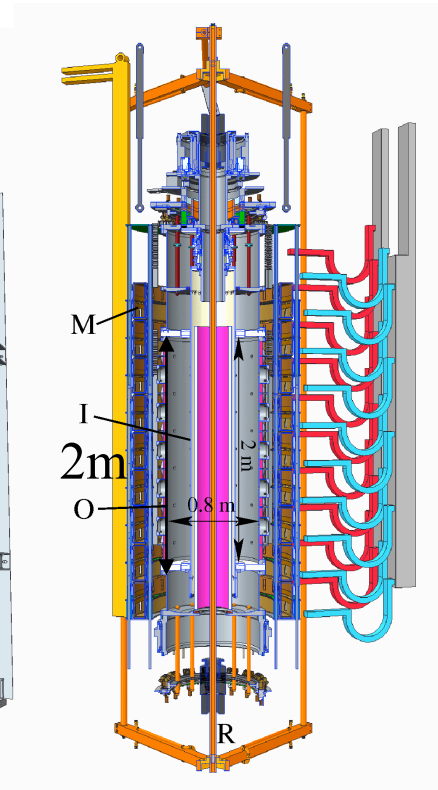
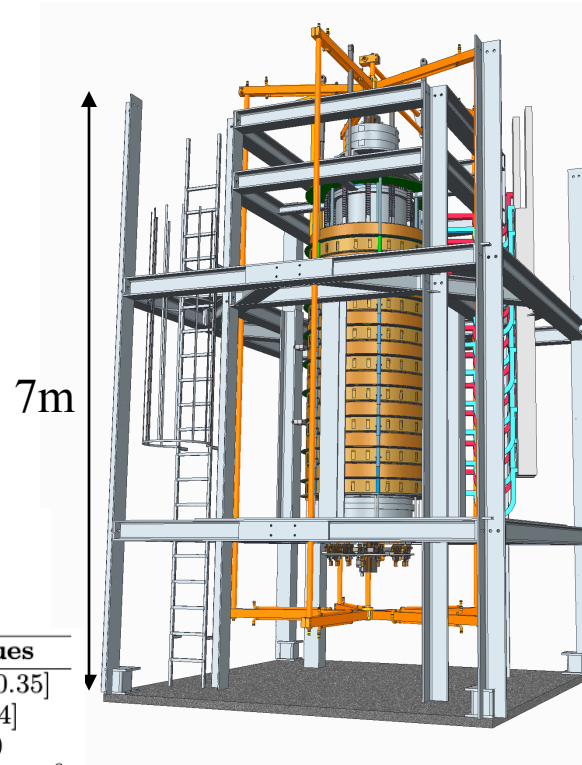


## MRI/TI experiment



# The new big, advanced TC device in DRESDYN

Physical Parameter	Values
$r_{in}$	0.2 m
$r_{out}$	0.4 m
$L_z$	2 m
$\Omega_{in}$	$\leq 2\pi \cdot 20$ Hz
$\Omega_{out}$	$\leq 2\pi \cdot 6$ Hz
Axial magnetic field ( $B_{0z}$ )	$\leq 150$ mT
Current through central rod (I)	$\leq 50$ kA
Conductivity ( $\sigma$ )	$9.5 \times 10^9$ S/m
Viscosity ( $\nu$ )	$6.512 \times 10^{-7}$ m <sup>2</sup> /s
Density ( $\rho$ )	920 kg/m <sup>3</sup>



Physical parameters of the DRESDYN MRI-experiment

Dimensionless Parameter	Definition	Values
$\mu$	$\Omega_{out}/\Omega_{in}$	(0.25, 0.35]
$\beta$	$B_{0\phi}(r_{in})/B_{0z}$	[0, 4]
Normalised height of the TC device	$L_z/r_{in}$	10
Renolds number ( $Re$ )	$\Omega_{in}r_{in}^2/\nu$	$\leq 7.72 \times 10^6$
Hartmann number ( $Ha$ )	$B_{0z}r_{in}/\sqrt{\rho\mu_0\nu\eta}$	$\leq 3778$
Magnetic Prandtl Number ( $Pm$ )	$\nu/\eta$	$7.77 \times 10^{-6}$
Magnetic Reynolds Number ( $Rm$ )	$RePm$	$\leq 40$
Lundquist Number ( $Lu$ )	$Ha\sqrt{Pm}$	$\leq 10$
Azimuthal Hartmann number ( $Ha_\phi$ )	$B_{0\phi}(r_{in})r_{in}/\sqrt{\rho\mu_0\nu\eta}$	$\leq 1259$
Azimuthal Lundquist Number ( $Lu_\phi$ )	$Ha_\phi\sqrt{Pm}$	$\leq 3.51$

$$Re \sim 10^6 - 10^7$$

$$Rm_{max} \sim 40$$

$$Lu_{max} \sim 10$$

**MRI regime achieved !**

Non-dimensional parameters of the DRESDYN MRI-experiment

# Main Goals:

- To study the linear and nonlinear dynamics of SMRI specifically for the upcoming DRESDYN-MRI experiment
- To understand the saturation mechanism of SMRI in the *small- $P_m$*  regime
- To derive the dependence of the saturated SMRI amplitude with respect to different system parameters ( $R_m$ ,  $L_u$ ,  $P_m$ , ..)

# Equations of non-ideal MHD equations

$$\partial_t \mathbf{U} + (\mathbf{U} \cdot \nabla) \mathbf{U} = -\frac{1}{\rho} \nabla P + \frac{1}{\rho \mu_0} (\nabla \times \mathbf{B}) \times \mathbf{B} + \nu \nabla^2 \mathbf{U}$$

$$\partial_t \mathbf{B} = \nabla \times (\mathbf{U} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B}$$

$$\nabla \cdot \mathbf{U} = 0, \quad \nabla \cdot \mathbf{B} = 0$$

Equilibrium:  $\mathbf{u}_0 = (0, r\Omega(r), 0), \quad \mathbf{B}_0 = (0, 0, B_{0z})$

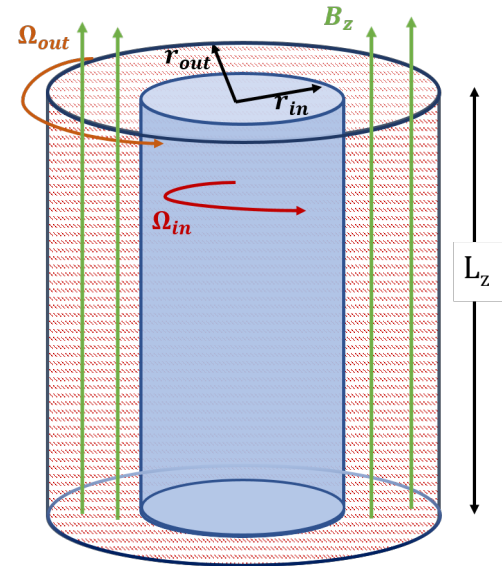
$$\Omega(r) = \frac{r_{out}^2 \Omega_{out} - r_{in}^2 \Omega_{in}}{r_{out}^2 - r_{in}^2} + \frac{(\Omega_{in} - \Omega_{out}) r_{in}^2 r_{out}^2}{r_{out}^2 - r_{in}^2} \frac{1}{r^2}, \quad \mu = \Omega_{out} / \Omega_{in} > 0.25 \text{ (Rayleigh-stable)}$$

Perturbations:  $\mathbf{u} = \mathbf{U} - \mathbf{U}_0, \quad \mathbf{b} = \mathbf{B} - \mathbf{B}_0 \propto \exp(ik_z z + im\phi)$

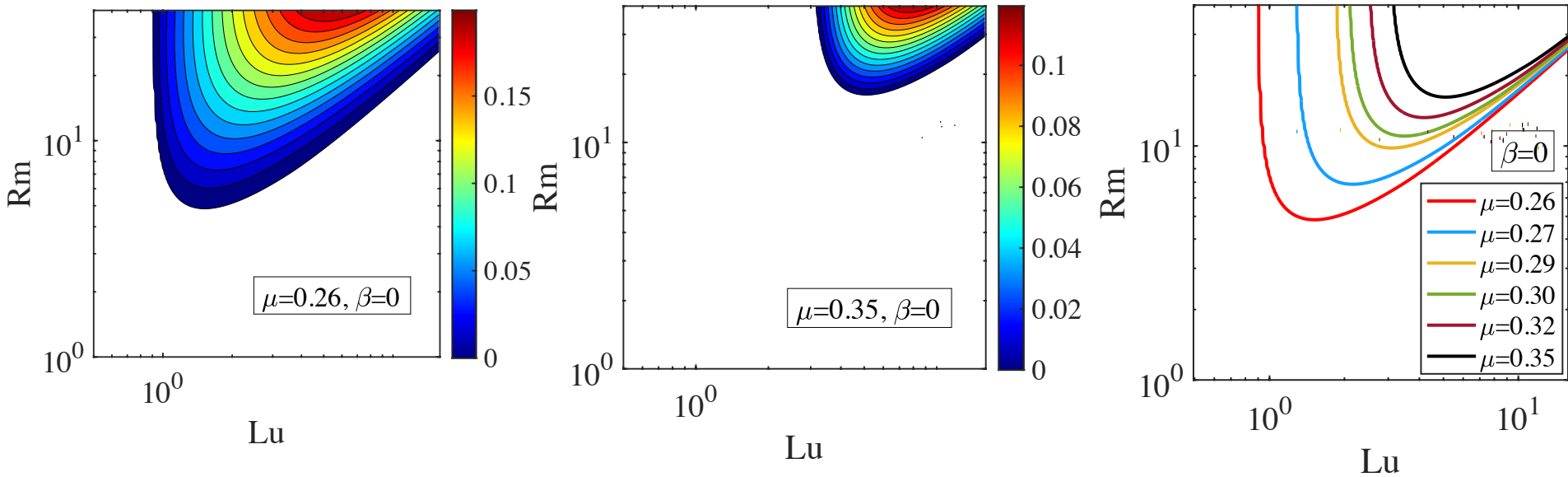
Boundary conditions: no-slip for velocity  
insulating for magnetic field

Pseudo spectral eigensolver based on Chebyshev decomposition

(Hollerbach & Rüdiger 2005)



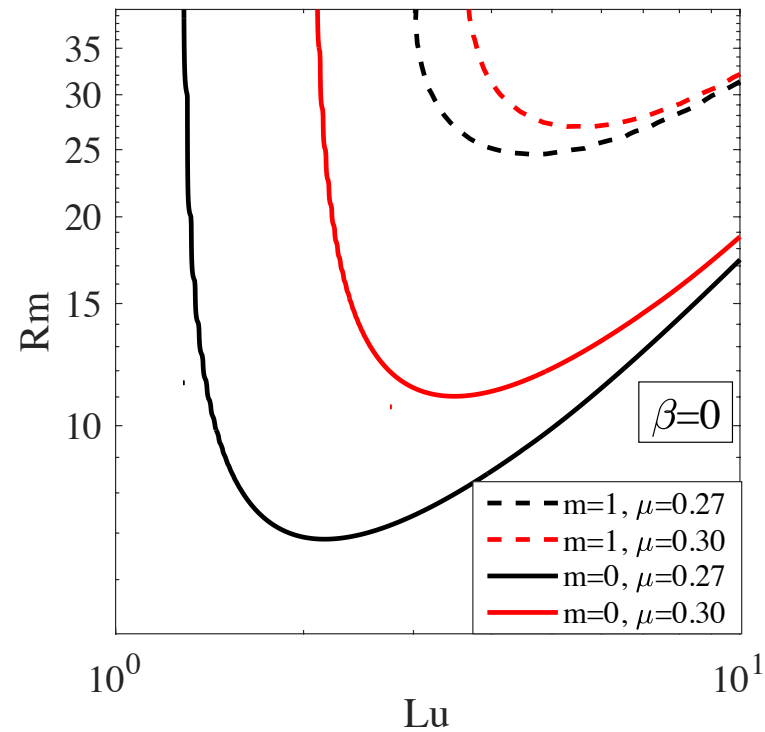
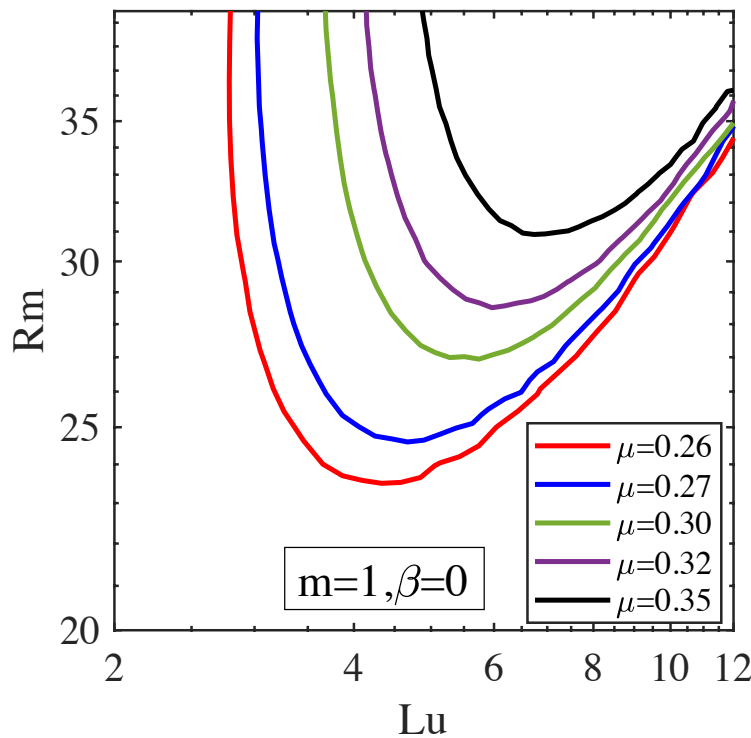
# Unstable regions in the Lundquist (Lu)- magnetic Reynolds (Rm) plane for axisymmetric ( $m=0$ ) SMRI — 1D Linear Stability Results



Mishra et al. 2022

**SMRI can be well detected within the parameter regime achievable in the DRES-DYN-MRI experiment, capturing its efficient growth range**

# Unstable regions in the Lundquist (Lu)- magnetic Reynolds (Rm) plane for non-axisymmetric ( $m=1$ ) MRI — 1D Linear Stability Results

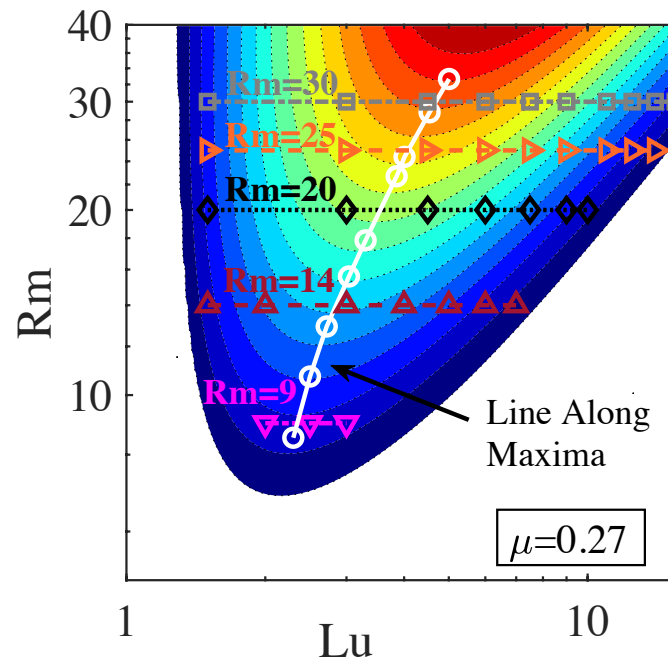


Mishra et al. 2024

**SMRI can be well detected within the parameter regime achievable in the DRESDYN-MRI experiment, capturing its efficient growth range**

# SMRI: Nonlinear Saturation and Evolution



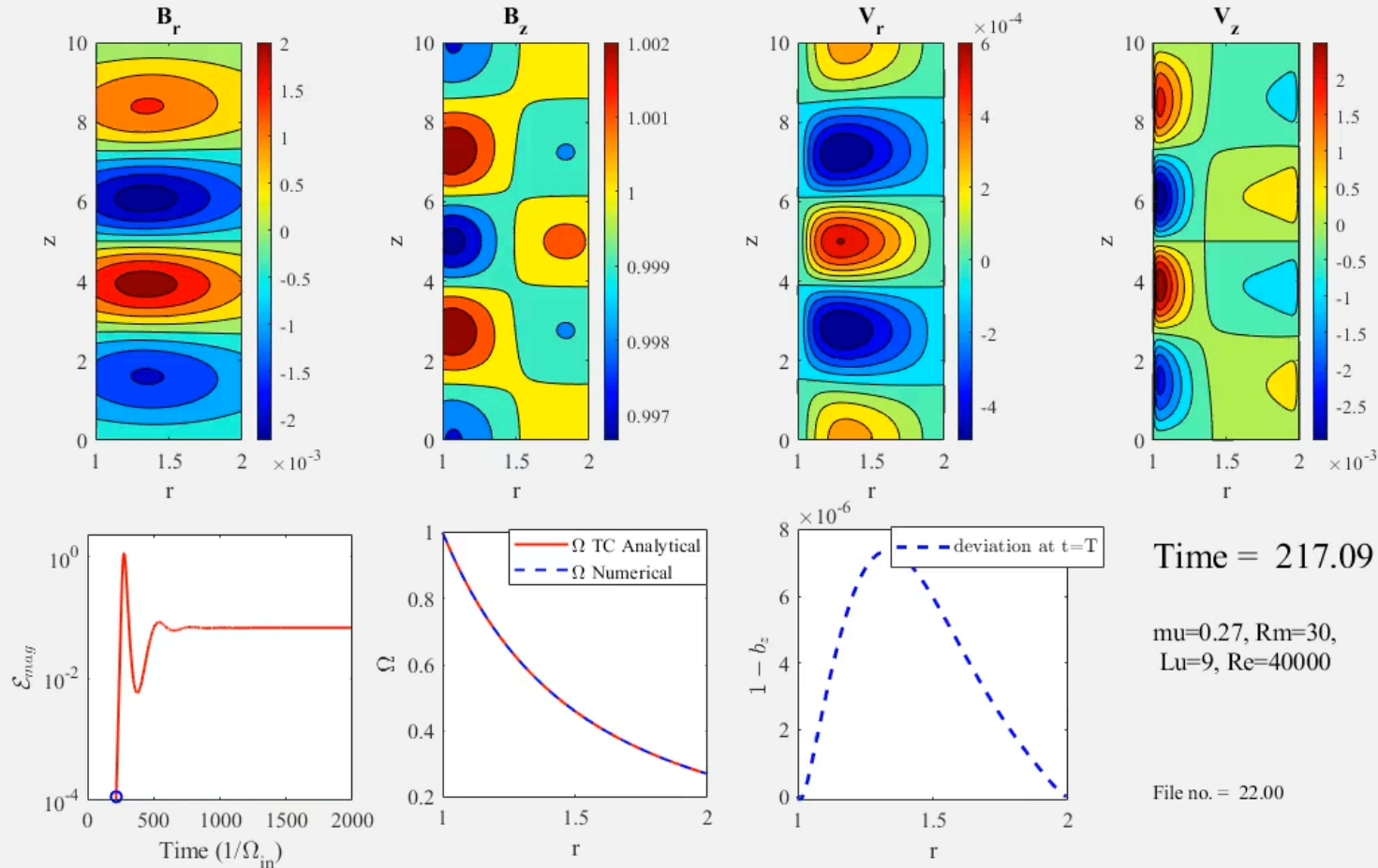


Instability region obtained from 1D linear stability analysis for  $\mu = 0.27$ ,  $Pm = 7.77 \times 10^{-6}$ , and  $k_{z,min} \geq 2\pi/L_z$

$$Re = [10^3, 4 \cdot 10^3, 7 \cdot 10^3, 10^4, 2 \cdot 10^4, 3 \cdot 10^4, 4 \cdot 10^4, 10^5]$$

We solved nonlinear MHD equations using pseudo-spectral code of Guseva et al. (2015)

# Nonlinear evolution in the (r,z)-plane



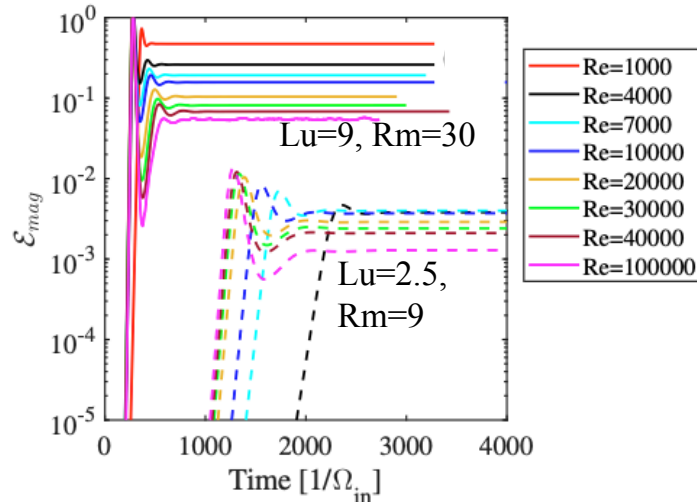
Saturation occurs via current sheet formation and resulting reconnection process

$$\mu = 0.27, Lu = 9, Rm = 30, Re = 4 \cdot 10^4$$

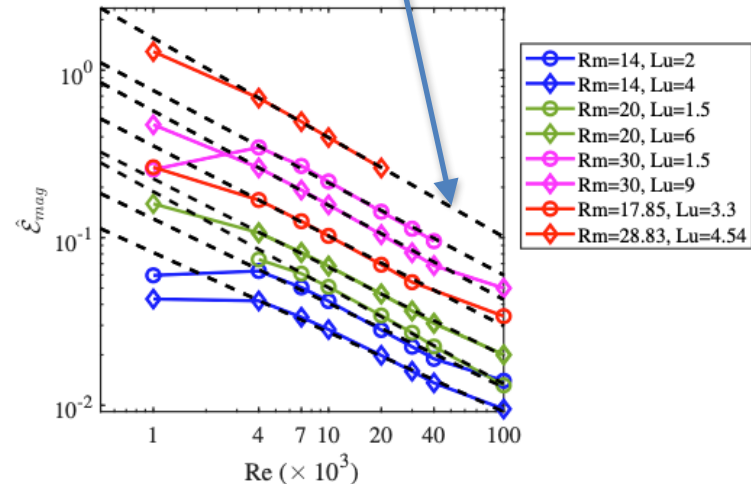
# Energy saturation & dependence on $Re$

Mishra et al. 2023

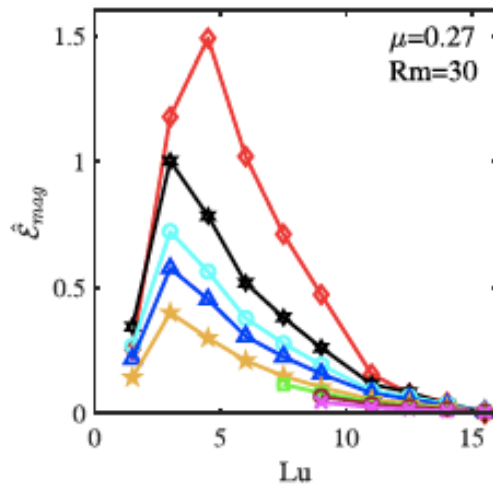
Time evolution of the volume integrated magnetic energy



fitting:  $Re^{-0.5}$

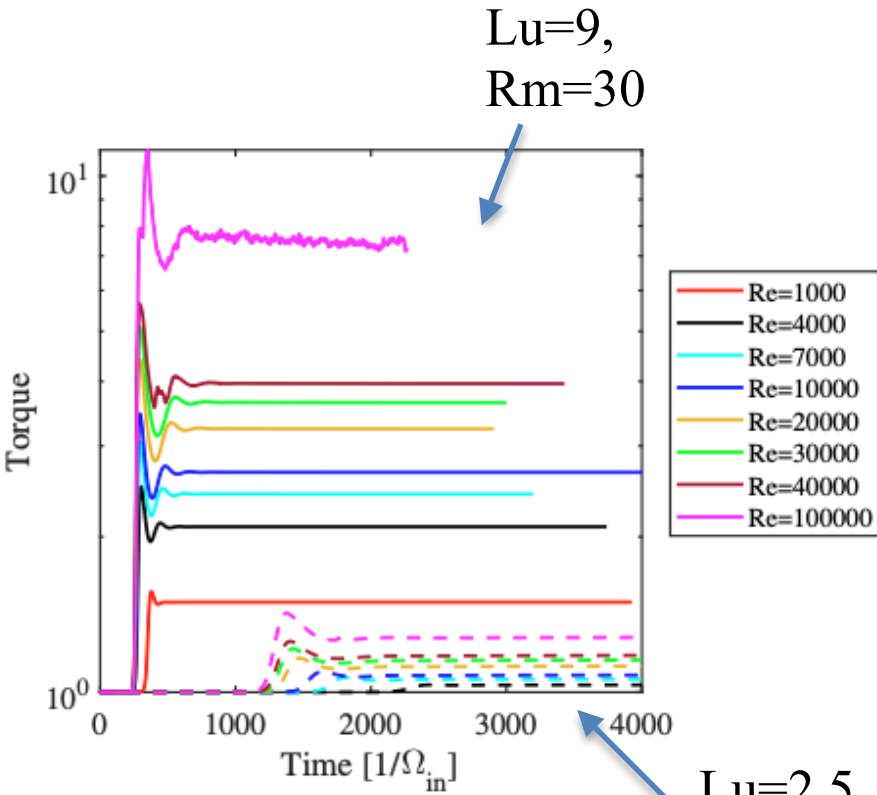


Saturated state magnetic energy as a function of  $Re$

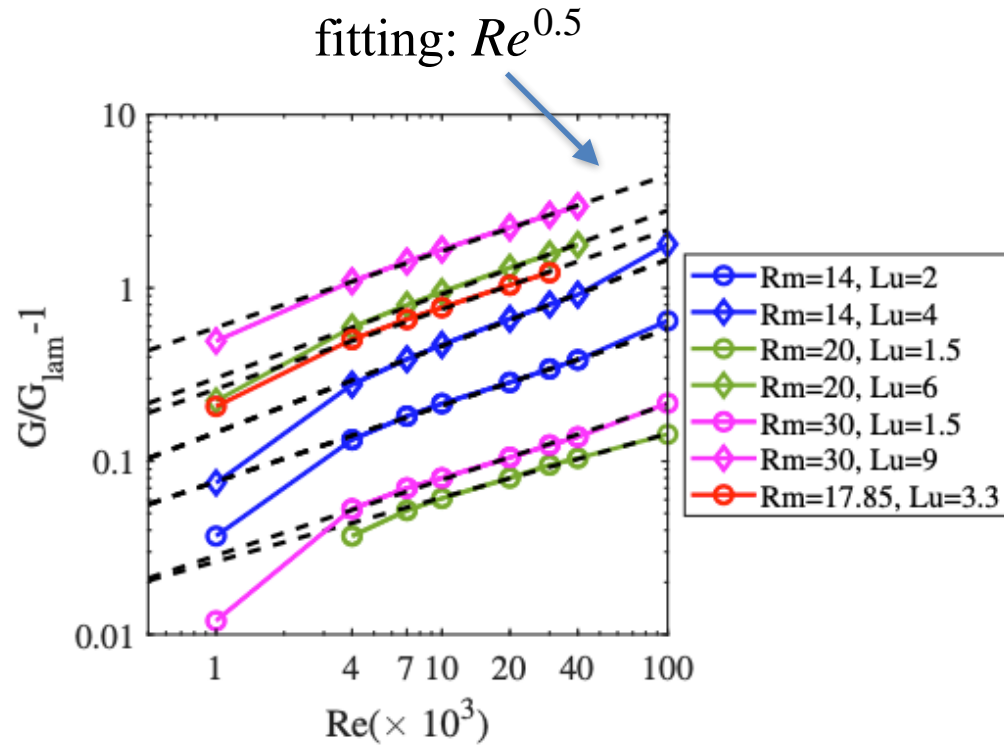


Dependence on  $Lu$

# Results: Torque & Dependence of turbulent torque on $Re$



Torque at the inner cylinder



Normalised Turbulent Torque as a function of  $Re$

$$G_{in,out} = - (r_{n,out}^3 / Re) \int \int \frac{\partial}{\partial r} (u_\phi / r) d\phi dz$$

Mishra et al. 2023

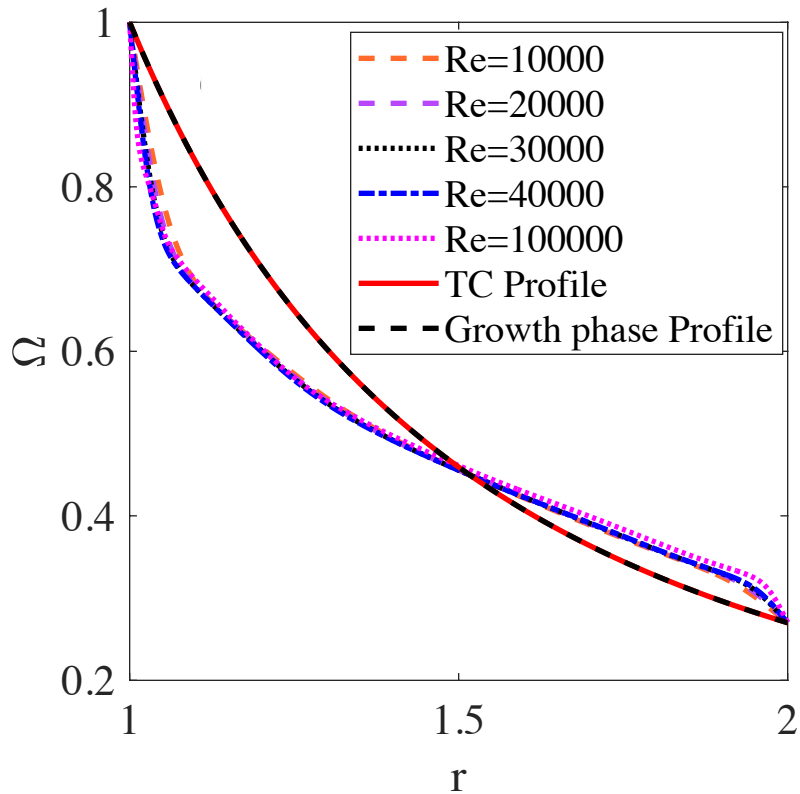
# Results: Amplitude of velocity and magnetic field perturbations

$\mu = 0.27$ (Lu, Rm)	$u$ ( $\Omega_{in} r_{in}$ )	$u$ (m/s)	$b$ ( $B_0$ )	$b$ (mT)
(2, 14)	0,0138	0,0808	0,0078	0,222
(4, 14)	0,0437	0,2560	0,0068	0,387
(1.5, 20)	0,0053	0,0443	0,0085	0,181
(6, 20)	0,0745	0,6234	0,0079	0,675
(1.5, 30)	0,0059	0,0740	0,0125	0,267
(9, 30)	0,1047	1,3142	0,1020	13,073

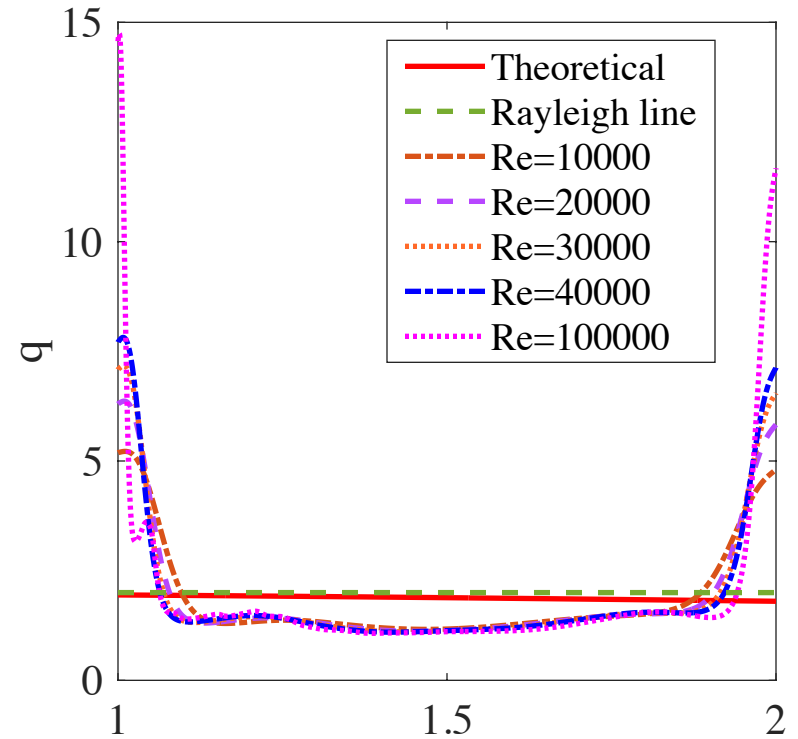
RMS velocity and magnetic field perturbations expected in the upcoming DRESDYN MRI-experiment (found by extrapolating power-laws to  $Re \sim 10^6$ )

# Deviation of $\Omega$ from TC profile & local shear $q$

Mishra et al. 2023

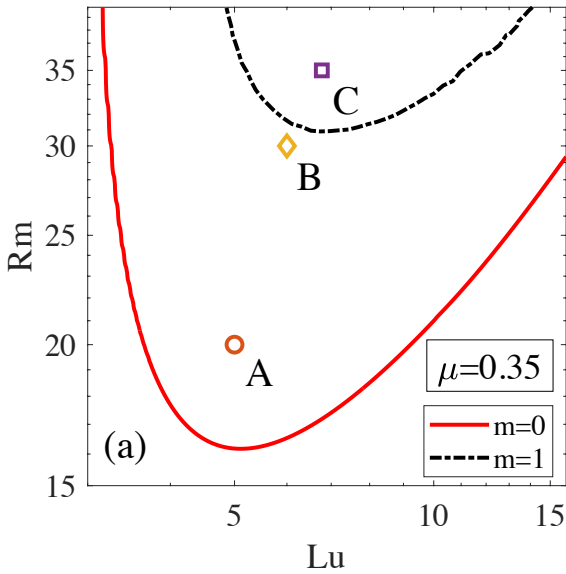


Rotation profile in saturated state

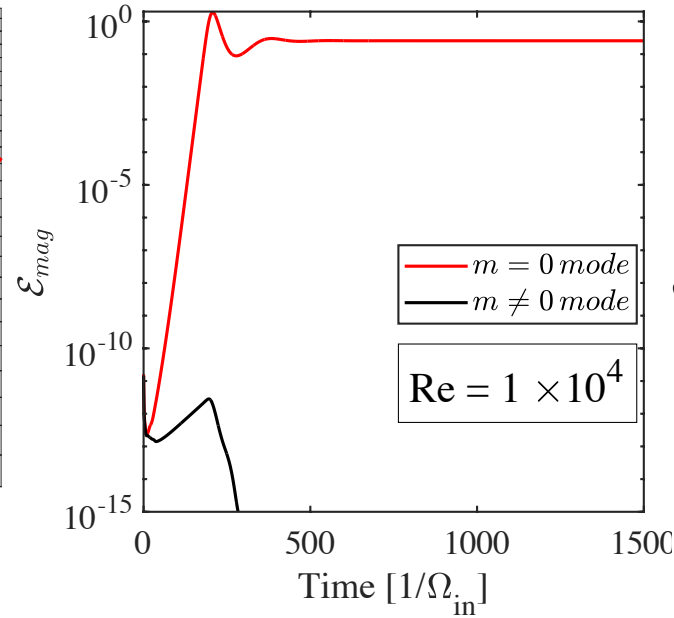


$$\text{Local shear } q = -\frac{r}{\Omega} \frac{\partial \ln \Omega}{\partial \ln r} \text{ in saturated state}$$

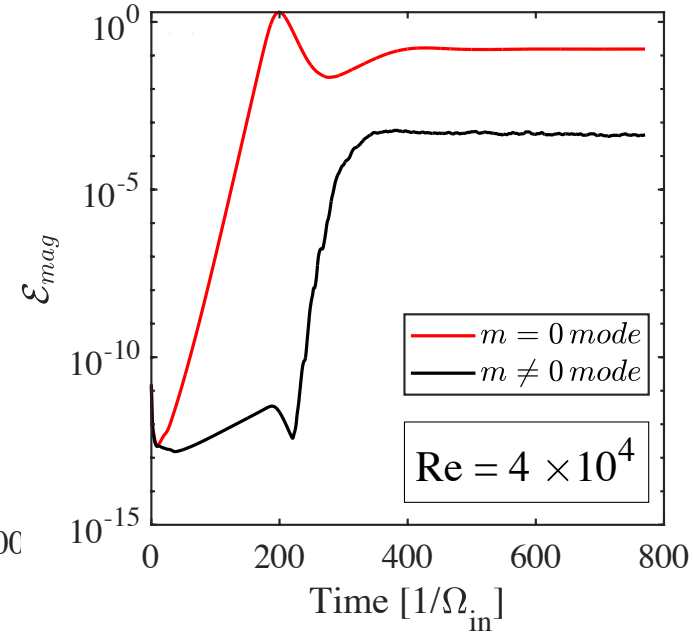
# Non-axisymmetric Modes of SMRI: Nonlinear evolution



Linear instability in  $(Lu, Rm)$ -plane

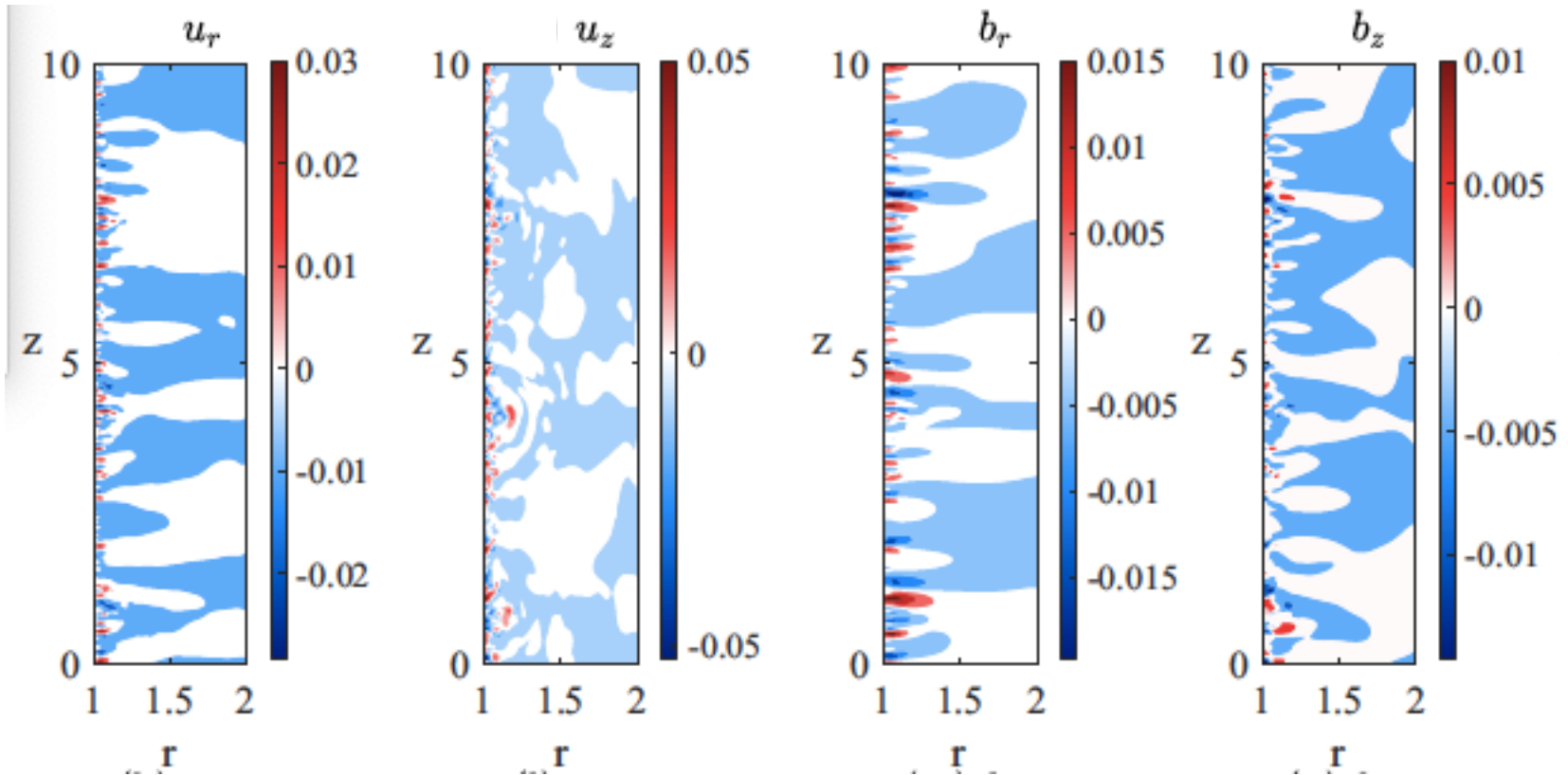


Evolution of magnetic energy at point C



Mishra et al. 2024

# Non-axisymmetric Modes of SMRI: Nonlinear evolution



Mishra et al. 2024



# Summary

- SMRI can be well detected within the parameter regimes achievable in the DRESDYN-MRI experiment, capturing its efficient growth range
- The nonlinear saturation occurs via magnetic reconnection process
- For different sets of  $(Lu, Rm)$ , the magnetic energy in the saturate state and the normalized turbulent torque scales with  $Re^{-0.5}$  and  $Re^{0.5}$ , respectively
- Magnitudes of velocity and magnetic field perturbation expected in the upcoming DRESDYN MRI-experiment were estimated

Please check out our papers on MRI in DRESDYN

Mishra, Mamatsashvili & Stefani, 2022, *Phys. Rev. Fluids*, **7**, 064802 (arXiv: 2112.01399)

Mishra, Mamatsashvili & Stefani, 2023, *Phys. Rev. Fluids*, **8**, 083902 (arXiv: 2211.10811)

Mishra, Mamatsashvili & Stefani, 2024, *Phys. Rev. Fluids*, **9**, 033904 (arXiv: 2307.16295)

# Future work

- Investigation of MRI in finite-length cylinders in **DRESDYN** and **Princeton** experiments at small  $Pm \ll 1$  and high  $Re > 10^4$ , taking into account the endcap effects: Ekman layers/circulations and Stewartson-Shercliff layers
- Onset, saturation and nonlinear evolution of SMRI under the influence of (insulating/conducting) endcaps in both MRI-experiments
- Dependence (scaling) of the saturated states on the system parameters (Lu, Rm, Pm, cylinder rotation rates, etc.)
- Detailed comparison with the experimental outcomes from DRESDYN and Princeton MRI-experiments

# Thank you for your attention

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